

Fig. 2: Comparison of measurement and simulation

level at the housing and by agreement in resonance frequencies. This comparison is

necessary in order to draw conclusions as to the plausibility of the model. A resonant frequency examination

"Good agreement between the simulation model and actual measurements at the gearbox housing was noted."

of the gear system was also performed. However, its validity is limited, as the stiffnesses in the highly non-

linear gear model change constantly. Good agreement between the simulation model

> and actual measurements at the gearbox housing was noted, permitting the conclusion that high model quality is possible

with a comparatively simple model without dynamic roller bearing models.

Based on this, the following steps are recommended for the future:

- Creation of SIMPACK models of parameterizable standard final drive
- Improvement in roller bearing and gear wheel models
- Full integration in development process

## **LITERATURE**

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[4] Weidemann, H.-J. (2003): Schwingungsanalyse in der Antriebstechnik. Berlin, Heidelberg, New York: Springer Verlag.

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## **SIMPACK Academy in 2013**

## **Fundamentals of Multi-Body System Dynamics**

## 30-31 October 2013, Hotel Seitner Hof, Pullach/Munich, Germany

Speaker: Prof. Dr. Oskar Wallrapp

Multi-Body Dynamics is one of the most prominent subjects of mechanical, mechatronics and biomechanical engineering. A brief knowledge of kinematics and dynamics is essential for efficient usage of multi-body programs like SIMPACK. This course gives a detailed overview of the kinematics and dynamics of rigid bodies in multi-body systems.

At the end of the academy, participants will be able to understand the motion of rigid bodies attached by arbitrary joints and forces, setup small subsets of equations of MBS motion, and interpret the results of multi-body dynamics simulations.

For more information and registration please visit: www.simpack.com/simpack\_academy.html



