

Working with SIMPACK Automotive+, Release 8.5

Marcus Schittenhelm,
INTEC GmbH

Working with SIMPACK Automotive+, Release

Overview: 8.5

- ▶ General
- ▶ Model Setup/Preprocessing
- ▶ Modelling Elements
- ▶ Solver
- ▶ Postprocessing
- ▶ User Subroutines
- ▶ Interfaces

Working with SIMPACK Automotive+, Release

General

- ▶ Improved Open Model Window
- ▶ New Start Model and Userspecific New Model
- ▶ New Licensing Mechanism
- ▶ Multi Plattform Support
- ▶ **Userspecific Dimensions**
- ▶ First Version of New Documentation

Working with SIMPACK Automotive+, Release

General: Multi Plattform Support 8.5

Functionality:

- Only one SIMPACK MAIN installation for all platforms
- The user configuration of a SIMPACK user has been fully adapted to support multiple different hardware and operating system platforms for one user setup.

Advantage/Application Cases:

Multi platform architecture (NT, UNIX) within a company:

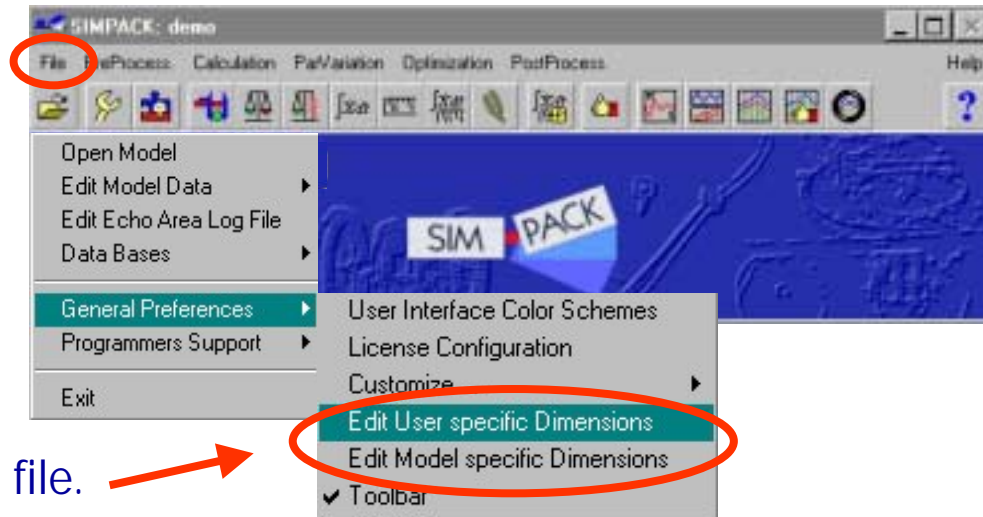
- > No need anymore to have different user configurations for different platforms
- > Less hard disc space required

Working with SIMPACK Automotive+, Release

General: Userspecific Dimensions 8.5

Functionality:

- SIMPACK executable dimensions no longer hard coded.
- Installation-, user- and model-specific dimensions configuration file.
- No recompile necessary after changing required dimensions.



Advantage/Application Cases:

- > User can always work with an optimized set of SIMPACK dimensions.
- > No special SIMPACK version necessary if dimension limit exceeded
- > Basis for completely automatical memory allocation mechanism of later versions of SIMPACK.

Working with SIMPACK Automotive+, Release

Model Setup

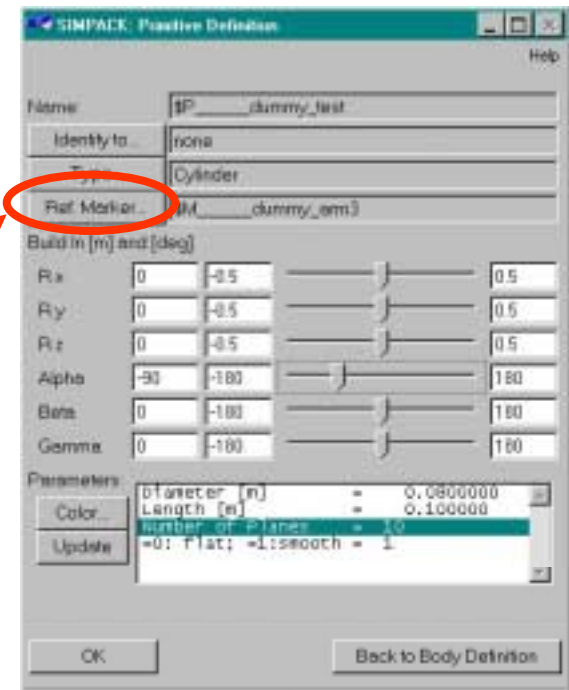
- ▶ Element Comments
- ▶ Support of all Units
- ▶ **Primitive Definition With Respect to Markers**
- ▶ **Complete Bushing Force Element Described by one File**
- ▶ **New Functionality within Parametrization**
- ▶ Tree Views for Marker and Modelling Element Selections
- ▶ Multi Select within Nominal Force Parameter Calculation
- ▶ Initializing States and Prestress Forces with Zero
- ▶ ***.LIST.dat files within Database Handling no longer necessary**
- ▶ **Time Excitations Defined in Substructures Usable in Main Structure**
- ▶ **Copy End of Run 1 to Linearization States**
- ▶ **Info about Inertia Tensor of Complete Model**
- ▶ Context Sensitive Display of Element Parameter Descriptions
- ▶ Miscellaneous (Colour Display, Marker Layout, Reload Model, ...)

Working with SIMPACK Automotive+, Release

Model Setup: Primitive Definition With Respect to Markers 8.5

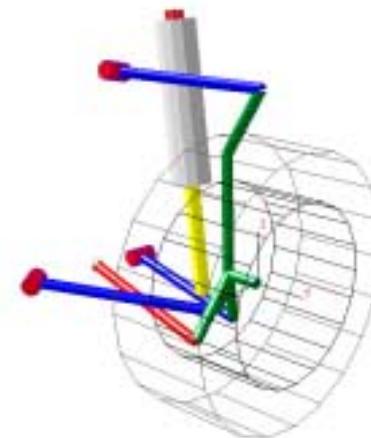
Functionality:

- All SIMPACK graphical primitive definition can be done with respect to existing marker positions/orientations
- No additional Sensor and Ensemble necessary



Advantage/Application Cases:

- > Easy and helpfull visualisation of orientation and displacements of e.g.: bushings, engine mounts, ...
- > No unnecessary sensor output values.



Working with SIMPACK Automotive+, Release 8.5

Model Setup: Complete Bushing Force Element Described by one File

Functionality:

- Definition of a complete ($c_{trans/rot}$, $d_{trans/rot}$) bushing referring only one single Input Function Set from database.
- Linear or nonlinear in any combination.
- Parametrization supported by new Substitution Variable Type.

Advantage/Application Cases:

- > Quick an easy model setup concerning bushings.
- > Clear and concise data structure



Working with SIMPACK Automotive+, Release

Model Setup: New Functionality within Parametrization

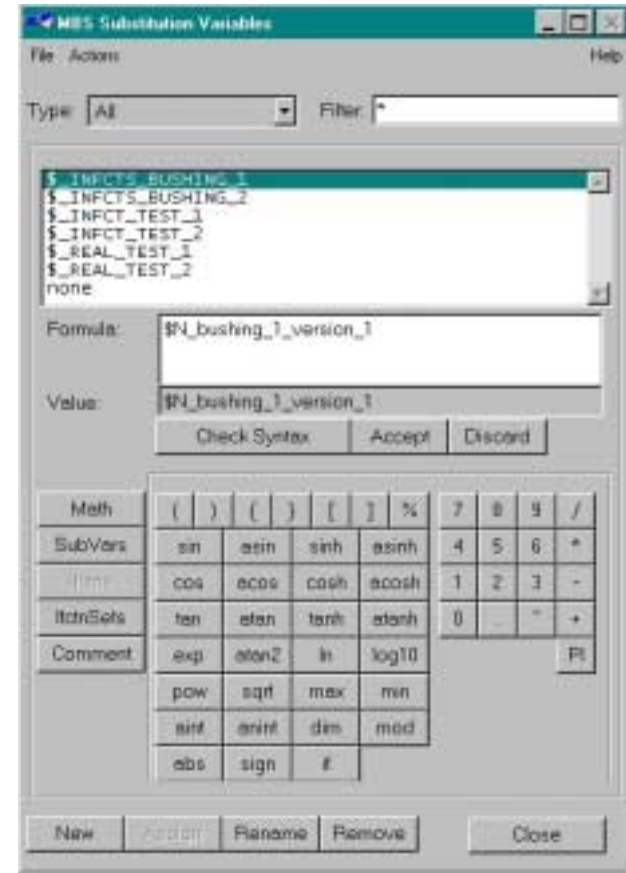
Functionality:

- Completely new GUI for editing Substitution Variables
- Substitution Variable window can always be kept open now
- Filtering while listing the Substitution Variables
- Parameterization of Input Functions and Input Function Sets
- New functionality "Arithmetic If"
- Rename of all Substitution Variables
- Arbitrary length of Substitution Variables
- Upper and Lower Case in combination

Advantage/Application Cases:

---> Extensive improvement of parametric model setup:

1. Intelligent parametrization using "Arithmetic If"
2. Clear data structure using parametrized Input Functions and Input Function Sets
3. ...

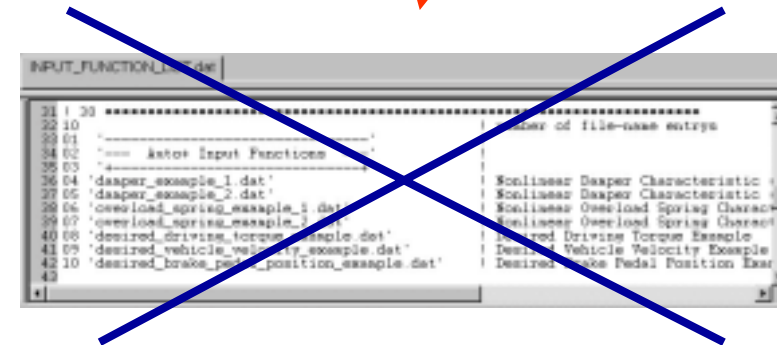
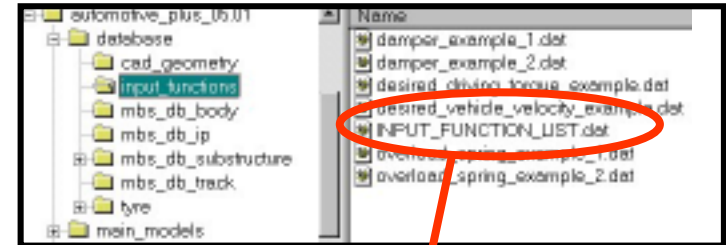


Working with SIMPACK Automotive+, Release 8.5

Model Setup: *.LIST.dat files within Database Handling no longer necessary

Functionality:

- „*_LIST.dat“ files no longer necessary
- Additionally still available if required
- All SIMPACK database directories affected



Advantage/Application Cases:

---> Much more comfortable model setup and data maintenance using SIMPACK database structures.

Working with SIMPACK Automotive+, Release 8.5

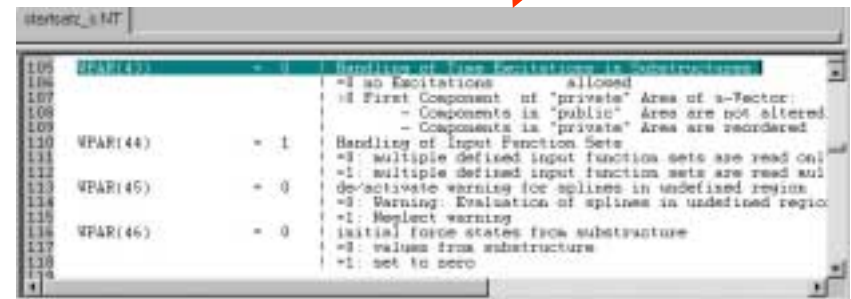
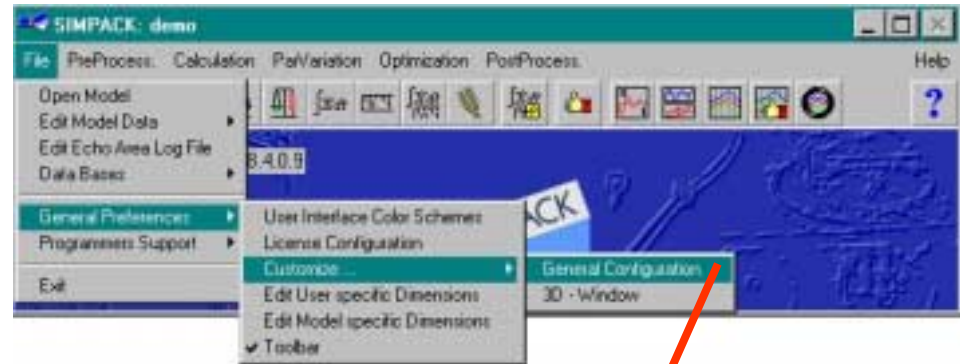
Model Setup: Time Excitations Defined in Substructures Usable in Main Structures

Functionality:

- Time Excitations defined in substructure also available in main models
- „Private“ and „public“ area of Time Excitation vectors
- Flag to switch on/off this functionality

Advantage/Application Cases:

- > Simple switch between different driving maneuvers by switching predefined substructures

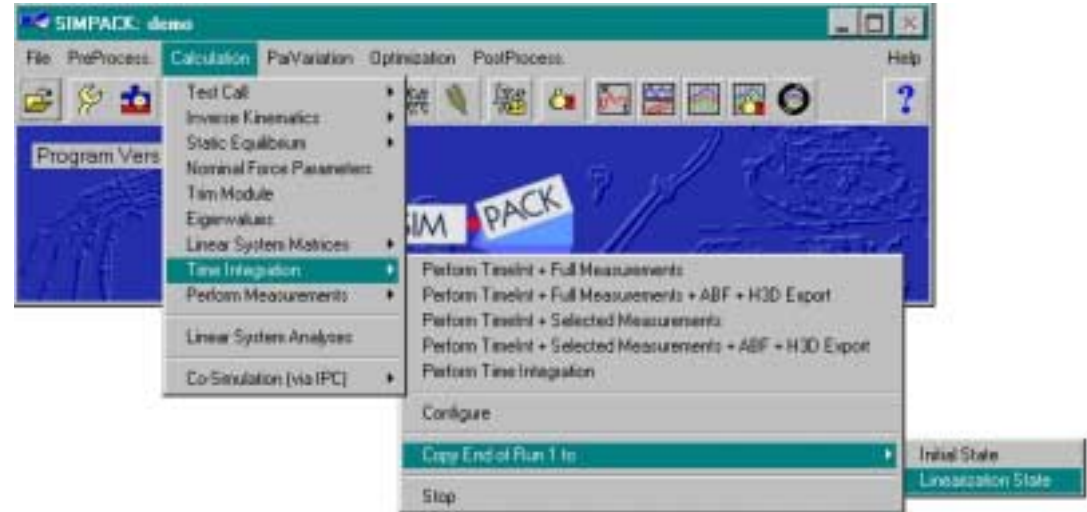


Working with SIMPACK Automotive+, Release 8.5

Model Setup: Copy End of Run 1 to Linearization State

Functionality:

- Copy end states of time integration runs to Initial State and/or to Linearisation State



Advantage/Application Cases:

- > Quasistatic Equilibrium States to use for Linearisation (Eigenvalues, Mode Shapes, Linear System Response, ...) without losing basic Initial State of the model.

Working with SIMPACK Automotive+, Release 8.5

Model Setup: Info about Inertia Tensor of Complete Model

Functionality:

Information about:

- mass
- centre of mass
- inertia tensor values
- main values of inertia tensor
- orientation of main axes

of a complete model

```

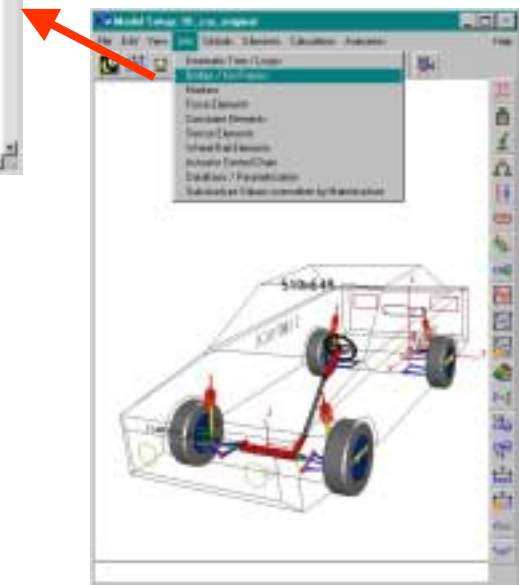
SIMPACK Model Information
-----
Total mass [kg] :
1.5715909+03

Center of Mass in initial position [m] :
0.45028900+00  1.82247940-01  7.28228840-02

Inertia-tensor relative to 'center of mass' and parallel to axis-coordinate system :
-----
-4.74660199+02  -2.23738709+00  1.08449079+02
-2.23738709+00  2.17164020+00  2.28170279-02
1.08449079+02  2.18175179-02  2.41489949+00

Inertia-tensor relative to 'center of mass' has following main-values :
-----
2.41489949+00  0.00000000+00  0.00000000+00
0.00000000+00  2.17164020+00  0.00000000+00
0.00000000+00  0.00000000+00  4.74660199+00

... in direction of following Main - Axis (relative to Esys) :
-----
0.46531370-01  -1.35005129-00  0.99984400-01  (X)
0.23140281-01  1.82121168+00  1.23271970-01  (Y)
0.78113771-01  -1.29603190-03  -1.58031610-01  (Z)
    
```



Advantage/Application Cases:

---> Check of model parameters concerning mass, centre of mass and inertia tensor parameters of all defined bodies.

Working with SIMPACK Automotive+, Release

Modelling Elements:

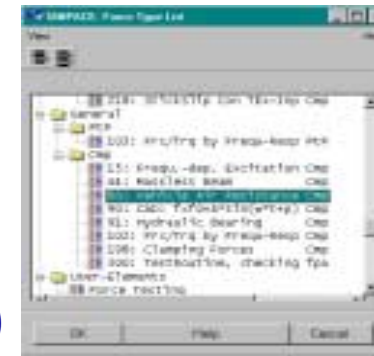
- ▶ New Air Spring Force Elements (3)
- ▶ New Flexicoil Force Element
- ▶ **New Air Resistance Force Element**
- ▶ New Force Elements: Gas Force, HLA, Hertzogan Contact
- ▶ New Track Module
- ▶ **New Tyre Modules (MF-MC, SWIFT, RMOD-K)**
- ▶ Creep Force Calculation in Accordance to Polach
- ▶ **Partial Coherence of Stochastic Excitations and $Mue(s,y) / Mue(x,y)$**
- ▶ **Congruent Marker**
- ▶ **Instant Centre/Axis Calculation and Representation**
- ▶ New Element Type: Function Expression
- ▶ **Input Functions: Extrapolation and New File Format**
- ▶ **Input Function Sets/Arrays: Handling and New File Format**
- ▶ Simulation of Switch Crossing

Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: New Air Resistance Force Element

Functionality:

- Simple Automotive Airdrag Model (only longitudinal component of air resistance)
- Complex Automotive Airdrag Model (all components of aerodynamic forces)
- Cross wind definition available



Advantage/Application Cases:

- > Driving dynamics within high speed manouvers
- > Acceleration behavior with airdrag

$$F_{x,AD} = -\frac{1}{2} \rho_{air} A_{vehicle} c_x(\gamma) v_{veh,xp}^3$$

$$F_{y,AD} = -\frac{1}{2} \rho_{air} A_{vehicle} c_y(\gamma) v_{veh,xp}^2 \text{sign}(\gamma)$$

$$F_{z,AD} = \frac{1}{2} \rho_{air} A_{vehicle} c_z(\gamma) v_{veh,xp}^2$$

$$M_{x,AD} = \frac{1}{2} \rho_{air} A_{vehicle} c_{M_x}(\gamma) v_{veh,xp}^2 l_{veh} \text{sign}(\gamma)$$

$$M_{y,AD} = -\frac{1}{2} \rho_{air} A_{vehicle} c_{M_y}(\gamma) v_{veh,xp}^2 l_{veh}$$

$$M_{z,AD} = -\frac{1}{2} \rho_{air} A_{vehicle} c_{M_z}(\gamma) v_{veh,xp}^2 l_{veh} \text{sign}(\gamma)$$

Working with SIMPACK Automotive+, Release

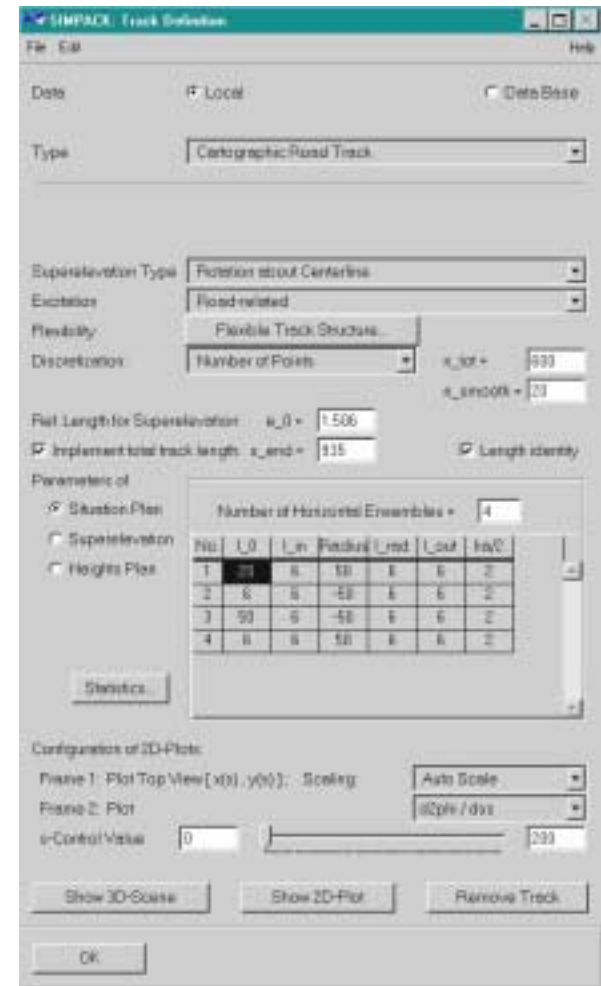
Modelling Elements: New Track Module 8.5

Functionality:

- New cartographic track with independent situation, super-elevation and (new) heights plan
- Extended road excitation and road friction functionalities

Advantage/Application Cases:

- > Definition of Closed Loop maneuvers with predefined tracks
- > Definition road excitations



Working with SIMPACK Automotive+, Release

Modelling Elements: New Tyre Modules (MF-MC, SWIFT, RMOD-K)

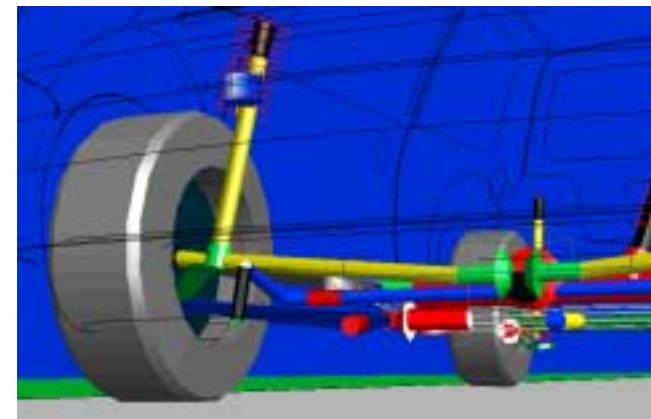
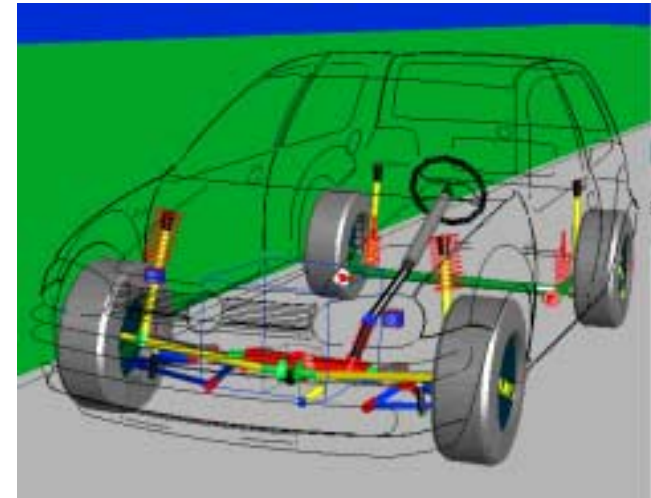
Functionality:

New Tyre Modules available with Force Element 49 (General SIMPACK Tyre):

- MF-MC Tyre by TMO (Motorcycle Tyre)
- SWIFT by TNO (Comfort Tyre Model)
- RMOD-K by GEDAS (Comfort Tyre Model)

Advantage/Application Cases:

- > Motorcycle applications (larger camber angles)
- > Ride and NVH complete vehicle analysis
- > Compatible and usable with special SIMPACK Automotive features (Vehicle Globals, Road Excitations, ...)



Working with SIMPACK Automotive+, Release 8.5

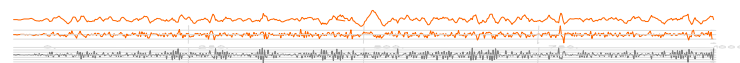
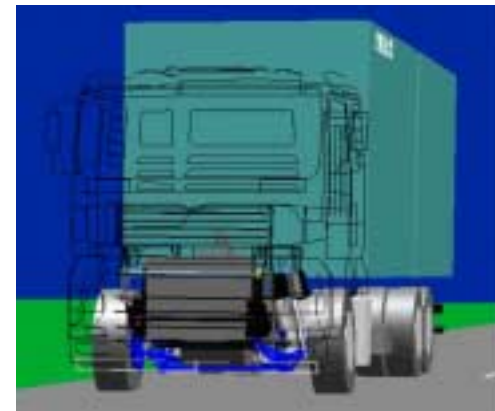
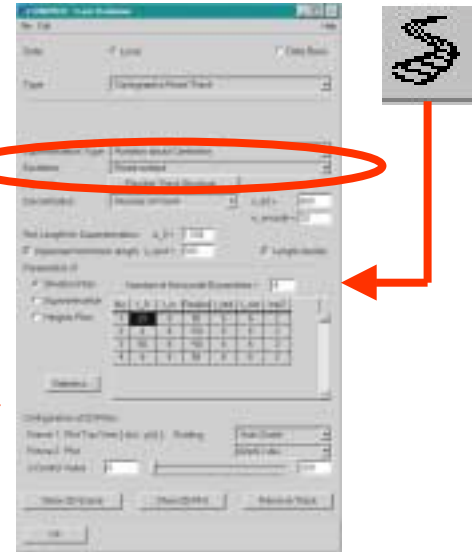
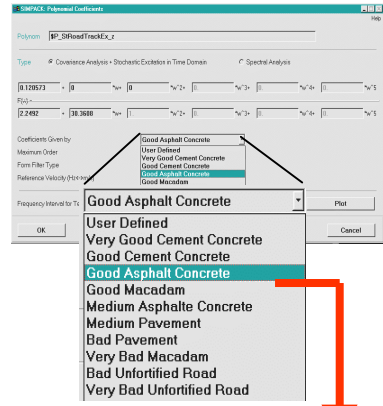
Modelling Elements: Partial Coherence of Stochastic Excitations

Functionality:

- Available within track definition
- Based on SIMPACK predefined polynomials describing road PSD's
- Different correlations of long and short wave length excitations between left and right vehicle side.
- Different types of coherence function definition.

Advantage/Application Cases:

---> Very comfortable definition of ride and NVH complete vehicle maneuvers

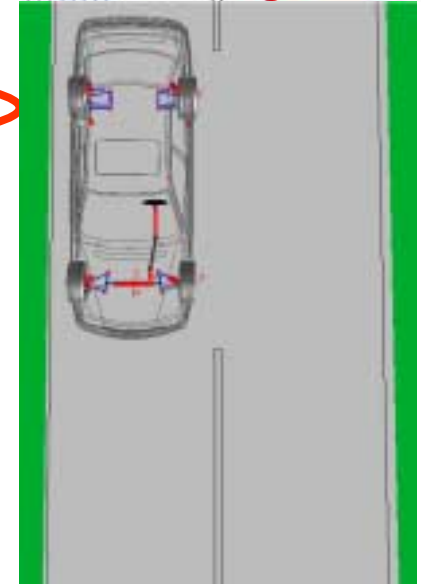
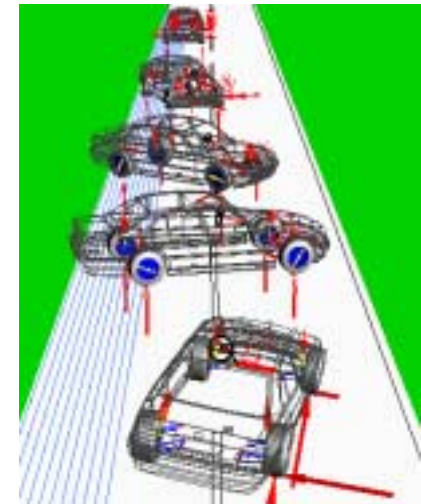
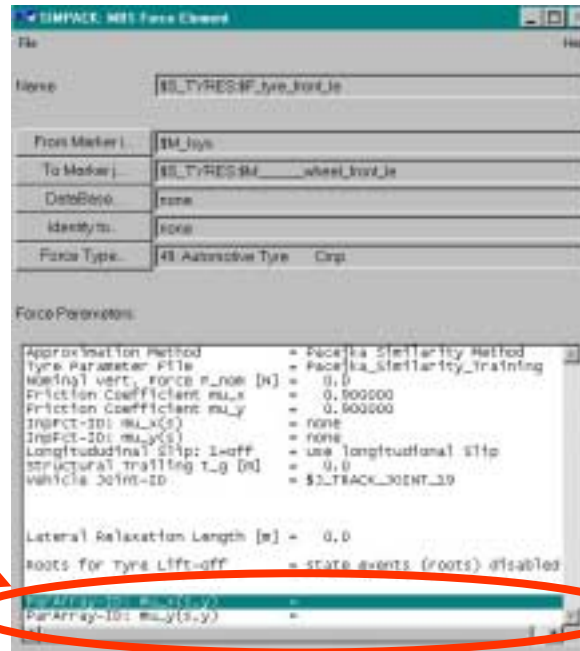


Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: Road Friction Coefficients $\mu(s,y)$ and $\mu(x,y)$

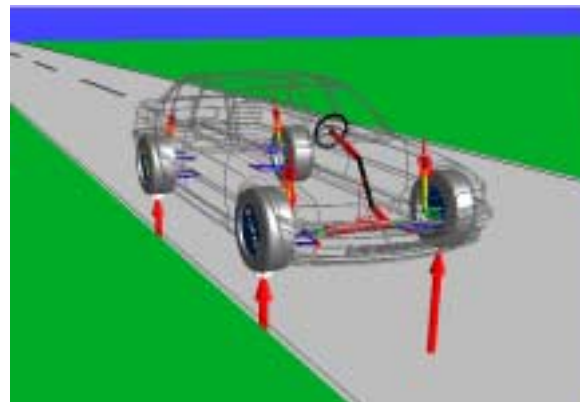
Functionality:

- Friction coefficient (μ) definition with SIMPACK Parameter Array
- Usable as $\mu(s,y)$ or $\mu(x,y)$ within tyre force element 49



Advantage/Application Cases:

- > Any kind of μ -split maneuvers

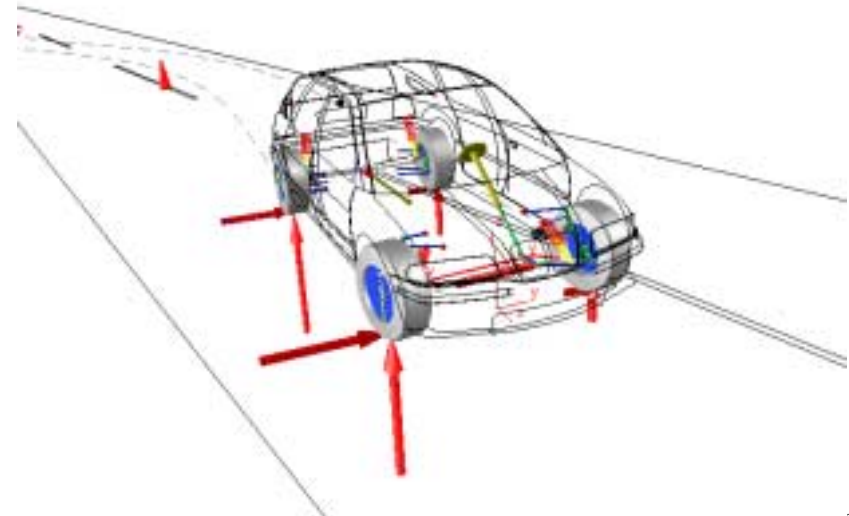
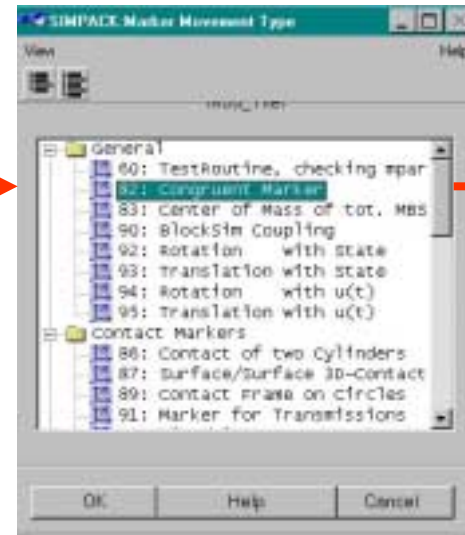


Working with SIMPACK Automotive+, Release

Modelling Elements: Congruent M8k5

Functionality:

- Moved Marker (Type 82) which is always at the same position as a marker on a different body.
- The position and orientation can be made congruent for all directions or selected directions only.
- Can have a velocity relative to the referenced marker or not, selectable by the user.



Advantage/Application Cases:

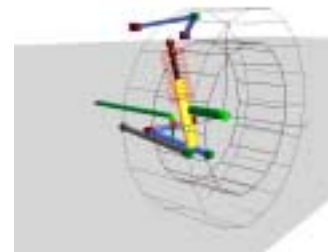
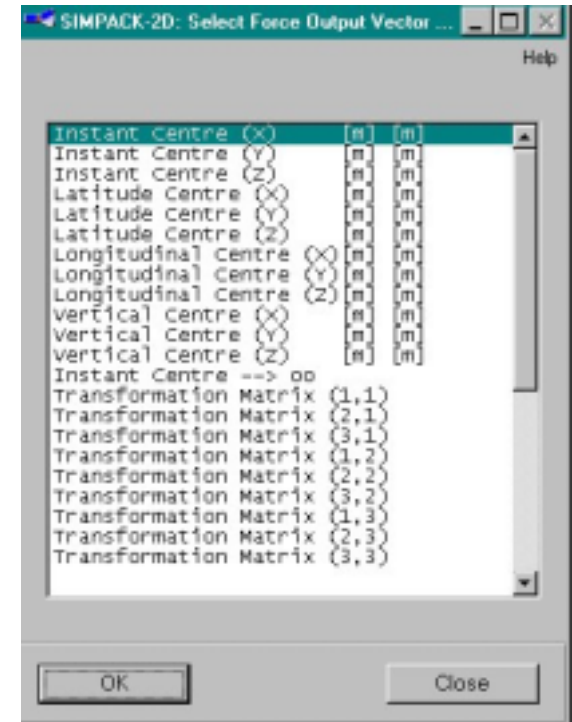
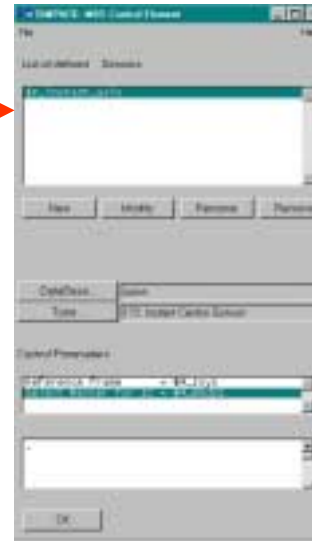
- > Any kind of moved views
- > representation of moved force contact points (e.g.: tyre forces)

Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: Instant Centre/Axis Calculation and Representation

Functionality:

- Sensor element to calculate instant axis
- Moved marker to visualize instant axis and instant centres
- Additional calculation and visualization of different instant centres (intersections of instant axis and user defined planes)



Advantage/Application Cases:

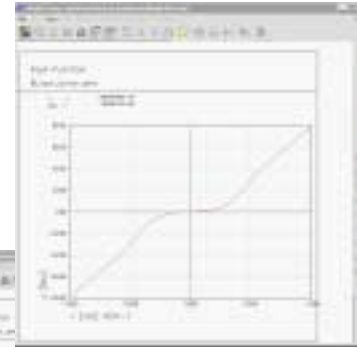
- > Visualization virtual steering axes
- > Visualization longitudinal and transversal instant centres
- > General visualization of instant axes

Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: Input Functions: Extrapolation and New File Format

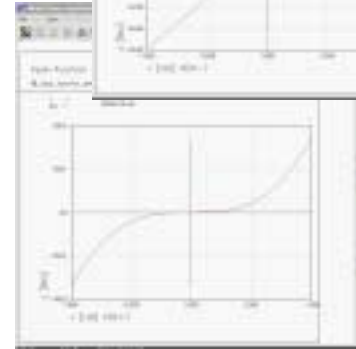
Functionality:

- Optimally switch to linear extrapolation of spline interpolation



New Input Function File Format (*.if2):

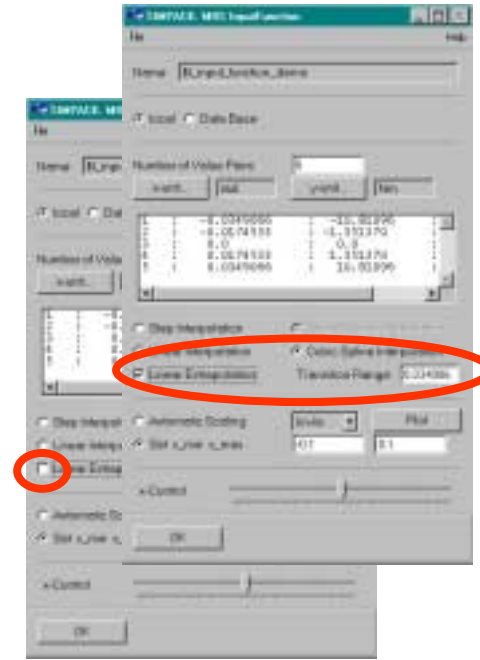
- No declaration of number of lines and number of valuepairs
- Definition of interpolation type and discontinuirties within the file
- Definition of units within the file additionally to model units
- Support by Sustitution Variables



```
inpFct_ascii_demoC*
1 $SIMPACK_Input_Function_Set0 | Release
2 1,1 | Format: 0/1/2 = ASCII/real/double
3 0
4
5
6 $I_Function_cubic | Input Function 3
7 1 | Interpolation Method: 0/1/2/3/4 = Step/CubicSpline/Linear/AkimaSpline/ConstGradient
8 1 2.000000E+00 0.000000E+00 | Extrapolation: 0/1 = CubicSpline/Linear : Transition Range
9 5.729577E+01 7.39969E-01 | UnitFactors = (x.y)[User] / (x.y)[SI] ((desl.(lbfitt))
10 angle torque | Unit Types
11 -2.000000E+00 -0.000000E+00 | x y d 1
12 -1.000000E+00 -1.000000E+00 | x y d 2
13 0.000000E+00 0.000000E+00 | x y d 3
14 1.000000E+00 1.000000E+00 | x y d 4
15 2.000000E+00 0.000000E+00 | x y d 5
16
```

Advantage/Application Cases:

- > Comfotabel definition of spline extrapolation areas
- > Clear data structure due to all infomation stored in new file format



Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: Input Function Sets: Handling and New File Format

Functionality:

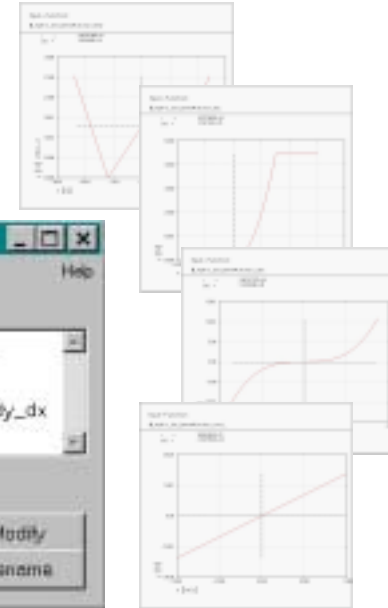
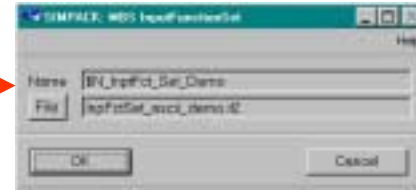
- Handling like any other SIMPACK element

New Input Function File Format (*.if2):

- No declaration of number of lines and number of valuepairs necessary
- Definition of interpolation type (Step/CubicSpline/Linear/AkimaSpline/ConstGradient) and discontinuities in the file
- Definition of units within the file additionally to model units
- Support by Sustitution Variables

Advantage/Application Cases:

- > Comfotabel definition of complete bushing force elements (linear and nonlinerar in combination) by only one file.
- > Clear data structure due to all infomation stored in new file format



Working with SIMPACK Automotive+, Release 8.5

Modelling Elements: Handling of Input Function Arrays

Functionality:

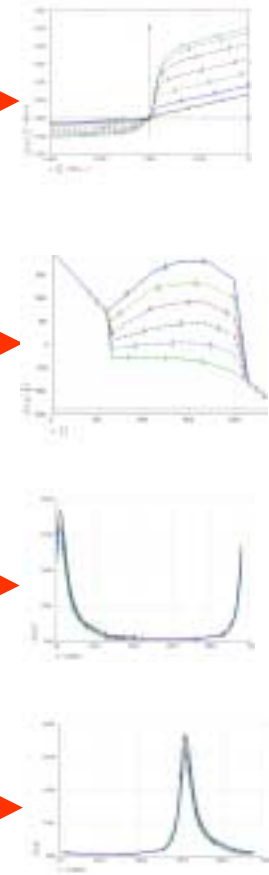
- GUI and Akima Spline Interpolation
- Optimally switch to linear extrapolation of spline interpolation
- Handling like any other SIMPACK element
- File Format (*.if3):

Advantage/Application Cases:

- > Semiactive dampers
- > Engine characteristic diagrams
- > ...



x	y	z
-0.500000	-5400.000	0.000
-0.070000	-5007.800	0.000
-0.250000	-4666.200	0.000
-0.172370	-4344.500	0.000
-0.125000	-4041.800	0.000
-0.0965940	-3796.400	0.000
-0.0779700	-3481.800	0.000
-0.0607980	-3088.200	0.000
-0.0462460	-2667.200	0.000
-0.0331720	-2246.400	0.000
-0.0236740	-1779.500	0.000
0.0	-1280.000	0.000
0.0236740	-788.800	0.000
0.0331720	-380.000	0.000
0.0462460	1188.00	0.000
0.0607980	2287.00	0.000
0.0779700	3481.800	0.000
0.0965940	4792.00	0.000
0.125000	6246.00	0.000
0.172370	8054.00	0.000
0.250000	10128.00	0.000
0.370000	12474.00	0.000
0.500000	15120.00	0.000



Working with SIMPACK Automotive+, Release

Solver 8.5

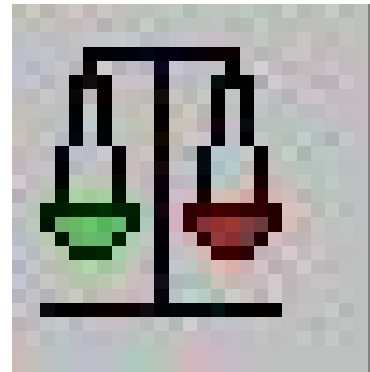
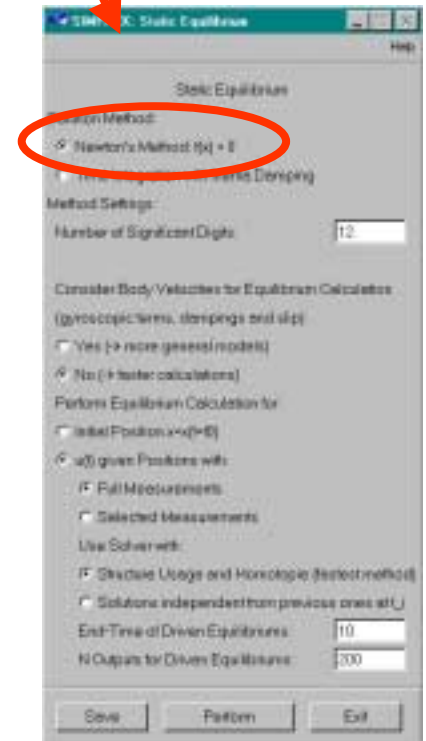
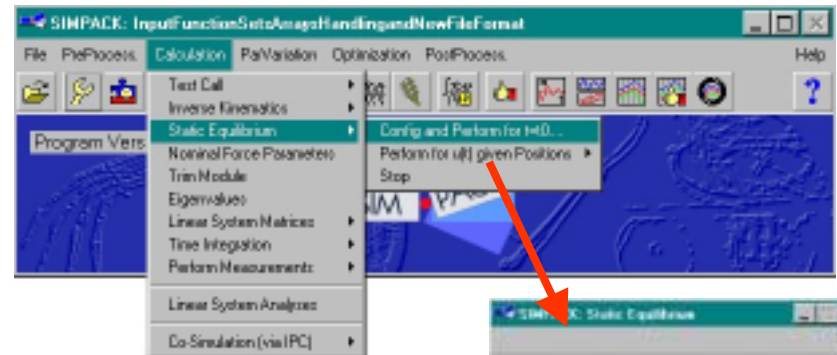
- ▶ Time Integration Configuration: Output Stepsize/Sampling Frequency
- ▶ Static Equilibrium: Newtons Method much more Robust and Faster
- ▶ **Static Equilibrium: New Solver Mode „Driven Equilibrium“**
- ▶ **Linerisation Process: Increased Speed and Robustness**
- ▶ **Eigenvalues: Improved Calculation Configuration and Representation**
- ▶ Force Element Consideration: Optionally with or without „rxF“
- ▶ Automatic Suggestion of Independent and Dependent Settings
- ▶ Parameter Variation: Max. Frequency for Critical Param. Calculation

Working with SIMPACK Automotive+, Release 8.5

Solver: Static Equilibrium: Newtons Method much more Robust and Faster

Functionality:

- Finding the static equilibrium with the "Newtons Method", i.e. by directly solving the nonlinear equations was made much more faster and robust for models with kinematic loops, i.e. constraints.

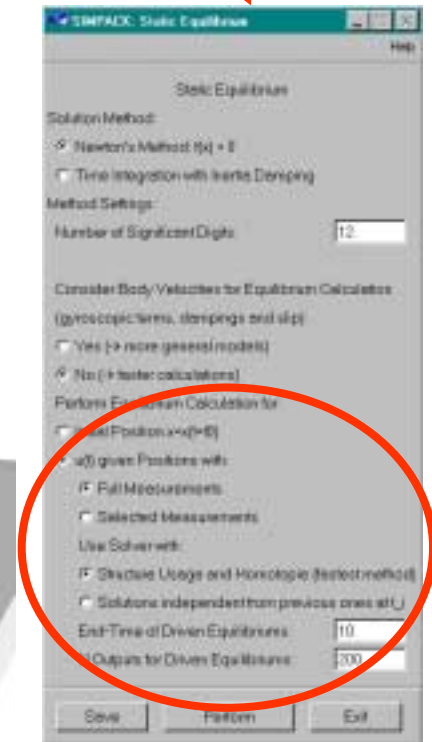
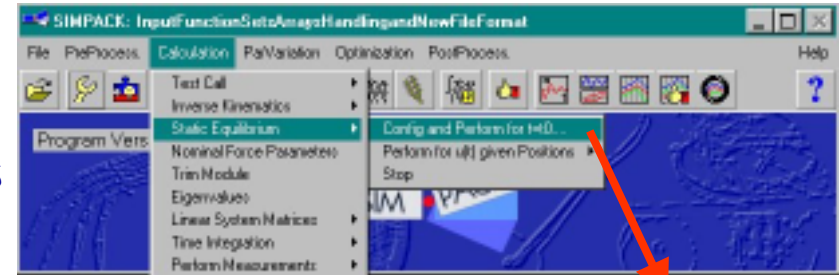


Working with SIMPACK Automotive+, Release 8.5

Solver: Static Equilibrium: New Solver Mode „Driven Equilibrium“

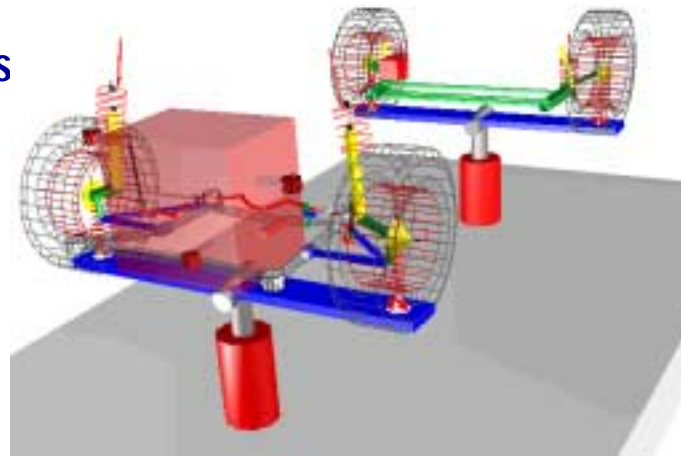
Functionality:

- Series of Static Equilibrium calculations
- Definition of required positions and forces by Time Excitations and u-Vectors
- Automatic generation of ‚static‘ time history



Advantage/Application Cases

- > No care about suitable damping parameters like in dynamic simulations
- > Elastokinematic testbeds
- > ...



Working with SIMPACK Automotive+, Release 8.5

Solver: Linerisation Process: Increased Speed and Robustness

Functionality:

- The linearization process was speed up significantly for closed loop systems
- Linearization process extendet for q-States
- Mode shape matrix available for absolut and relative body motions
- Calculation of kinetic and modal energy

Advantage/Application Cases:

- > Fast and robust linearization for closed loop systems
- > Much more comfortable calculation of Eigenvalues/Mode Shapes
- > Much more comfortable working with SIMPACK Linear System Analysis

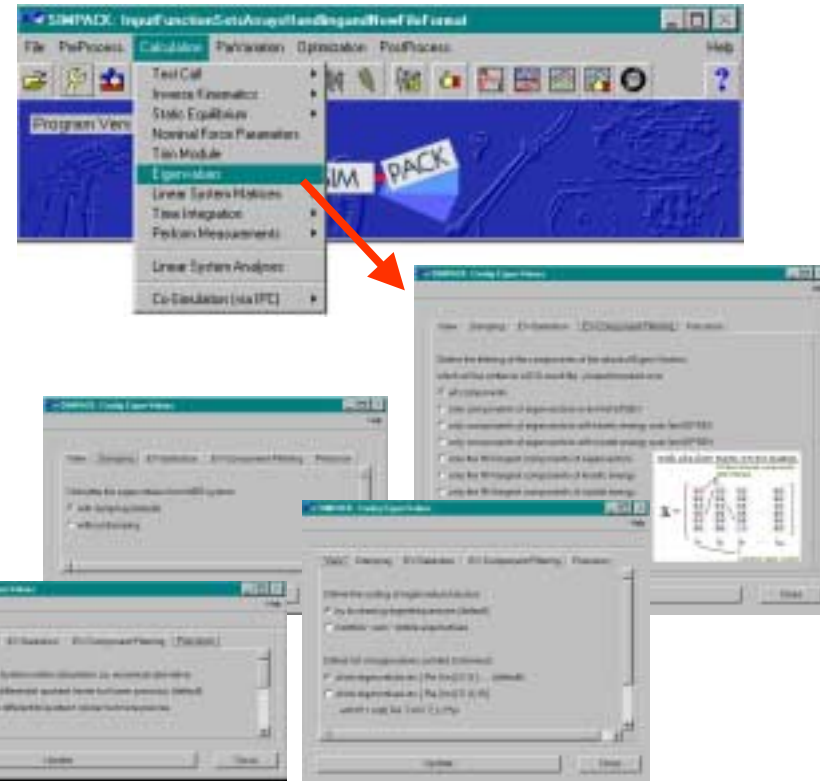


Working with SIMPACK Automotive+, Release 8.5

Solver: Eigenvalues: Improved Calculation, Configuration and Representation

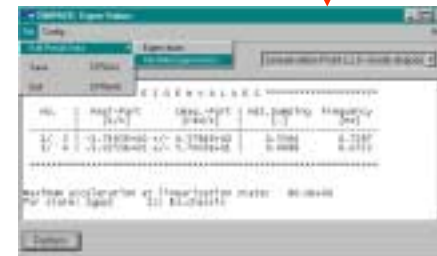
Functionality:

- Absolute modal results in addition to the relative modal results.
- Modal results are written to an ascii file
- Various filtering techniques for reducing the amount of information written to the modal result file
- Modal Analysis can be performed with or without regarding damping
- Energy partizipations are written out to the ascii modal result file



Advantage/Application Cases:

--> Much more comfortable calculation and representation of eigenvalues/mode shapes



Working with SIMPACK Automotive+, Release

Postprocessing 8.5

- ▶ **Animation Data with Display of Current Simulation Time**
- ▶ Animation Data without Reload
- ▶ Support of Alias Wavefront Files (*.obj) with Line Entity
- ▶ New 2D Filter
- ▶ Plot of Wheel Rail Profile Functions
- ▶ Aq-Sensor

Working with SIMPACK Automotive+, Release

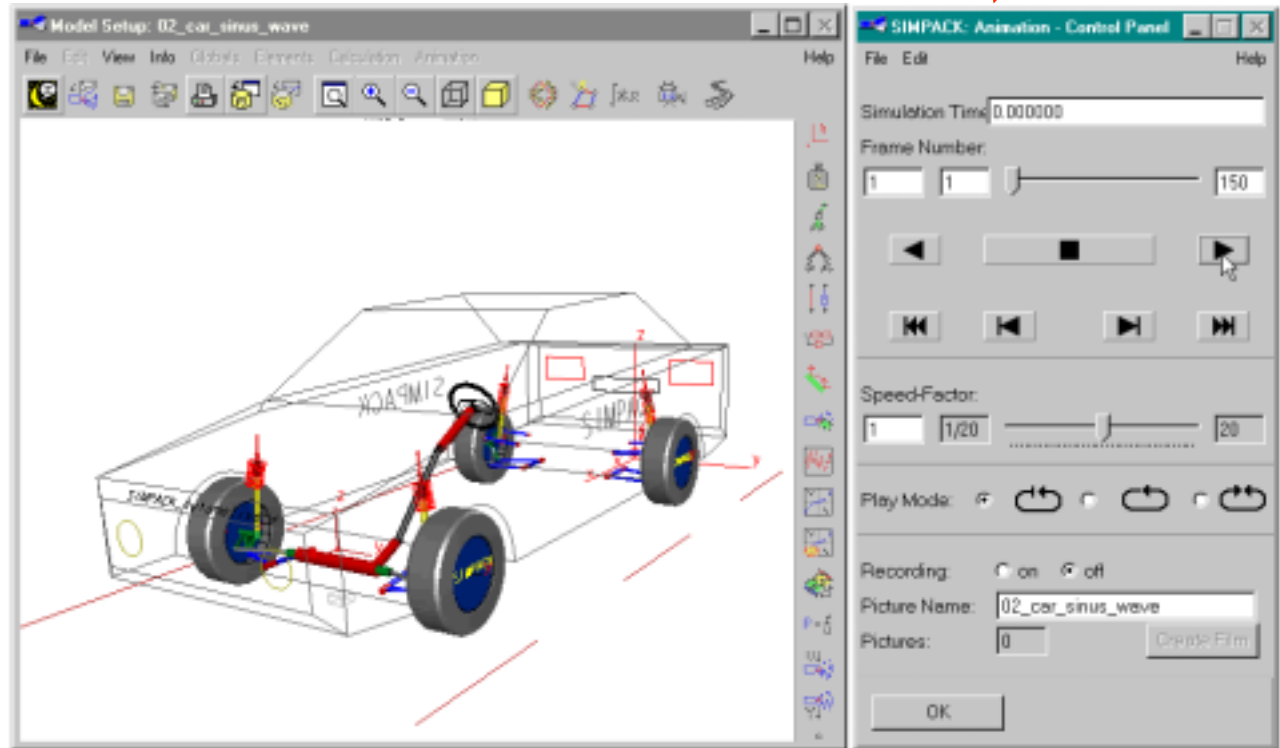
Postprocessing: Animation Data with Display of Current Simulation 8.5

Functionality:

- Display of current simulation time in 3D-animation control panel

Application Case:

--> Improved model/result check with 3D-animation



Working with SIMPACK Automotive+, Release

User Subroutines

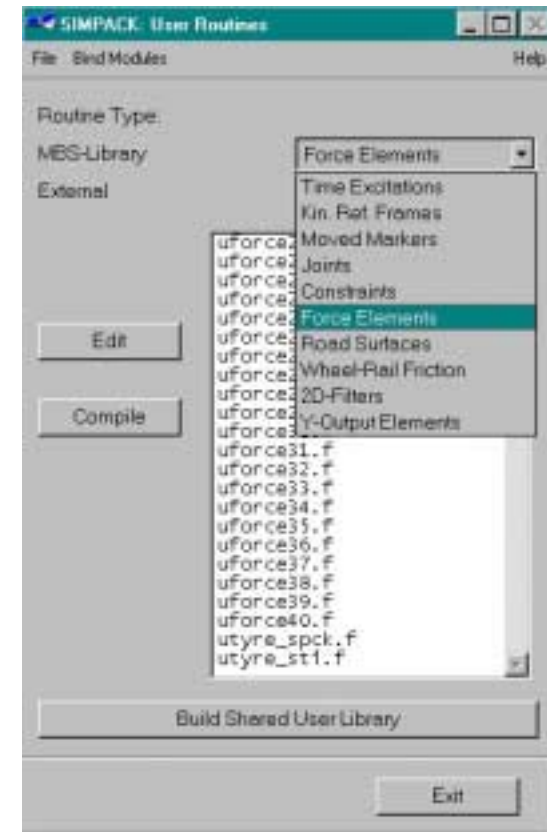
- ▶ String Elements for Transferring String Type Information
- ▶ **Only One Routine to Describe a Complete User element**
- ▶ Access Functions for all Data During Simulation
- ▶ New User Routine Type: Y-Output Vector
- ▶ Fully Comply with Shared Library Approach and Units

Working with SIMPACK Automotive+, Release

User Subroutines: Only One Routine to Describe a Complete Userelement **8.5**

Functionality:

- New GUI for SIMPACK user routines
- All User Routine functionalities necessary to describe a user element now available within only **one** file.



Advantage/Application Cases:

--> Ease the process of creating and maintaining user subroutines

Working with SIMPACK Automotive+, Release

Interfaces:

- ▶ FEMBS: SIMPACK GUI Integration and Functionality
- ▶ **ALTAIR (Hypergrap, HyperView, Motion View)**
- ▶ Inter Process Communication (IPC)/ AMESim:

Working with SIMPACK Automotive+, Release

Interfaces: ALTAIR (Hypergraph, HyperView, Motion View) 8.5

Functionality:



Interface to ALTAIR Inc. Products: Hypergraph/HyperView/Motion View

- Creating SIMPACK model data input files (*.sys and *.ani) with Motion View
- Transferring plotting data via the Altair Binary Format (ABF).
- Transferring animation data via the Altair Hyper 3D format (H3D)
- H3D format can also be used for deploying fully 3D graphics on the internet by utilizing the Hyper3D Player (small and light Plug In for NETSCAPE, Internet Explorer, ...)

Advantage/Application Cases:

- > Predefined SIMPACK model creation/ model transfer out of ADAMS models.
- > 2D and 3D Postprocessing with ALTAIR Inc. Products

